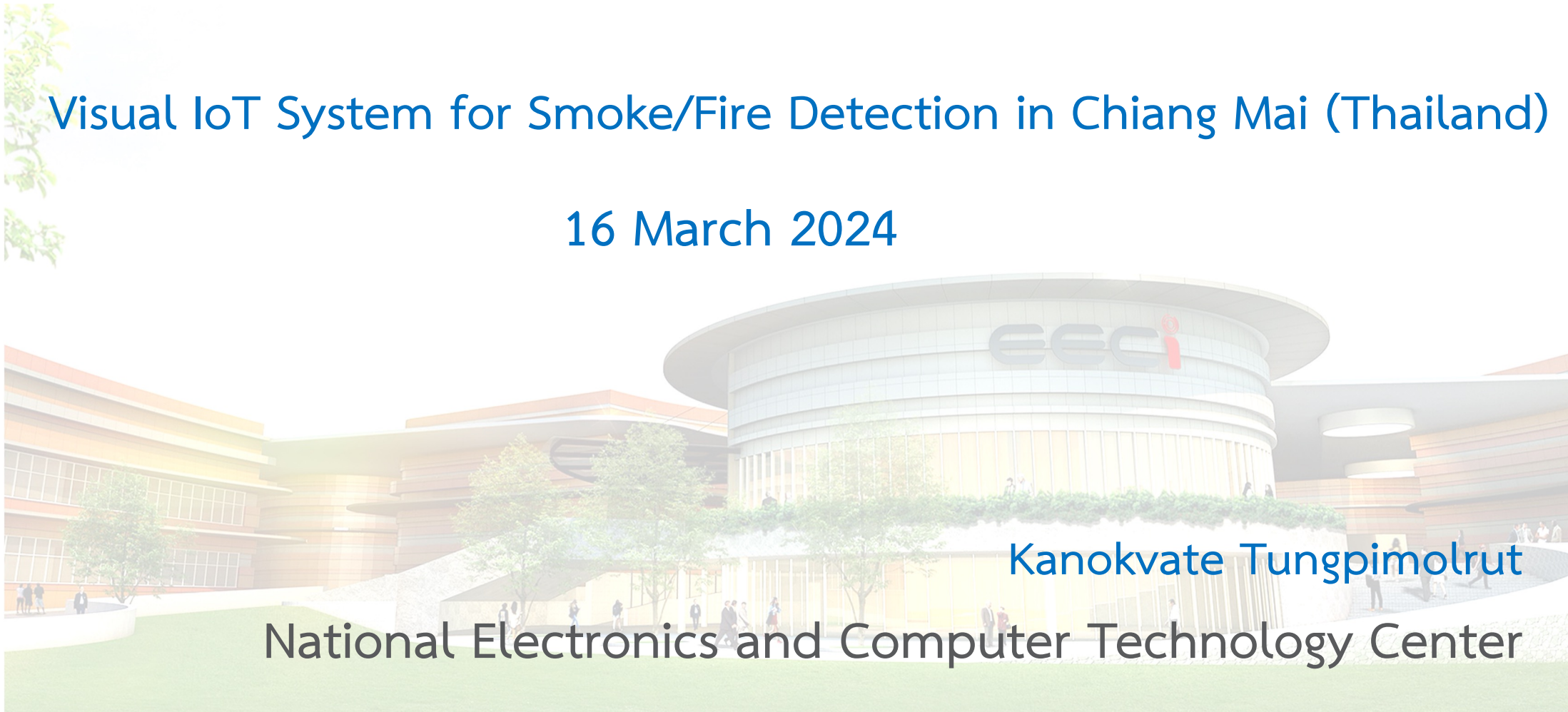




Visual IoT System for Smoke/Fire Detection in Chiang Mai (Thailand)

16 March 2024

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Outline of presentation



- Basic information of the project
- Dataset construction
- Smoke/Fire detection
- Hardware design and Installation

Basic Information of the project



Project Title : Visual IoT Network for Environment Protection and Disaster Prevention

Project Members :

National Institute of Information and Communications Technology (NICT)

University of Computer Studies, Yangon (UCSY)

National Electronics and Computer Technology Center (NECTEC)

Mapua University

National University of Laos (NUOL)

Sirindhorn International Institute of Technology (SIIT)

King Mongkut's Institute of Technology Ladkrabang (KMITL)



Acknowledgement:

This presentation is the output of the ASEAN IVO (http://www.nict.go.jp/en/asean_ivo/index.html) project, and financially supported by NICT (<http://www.nict.go.jp/en/index.html>).



Background :

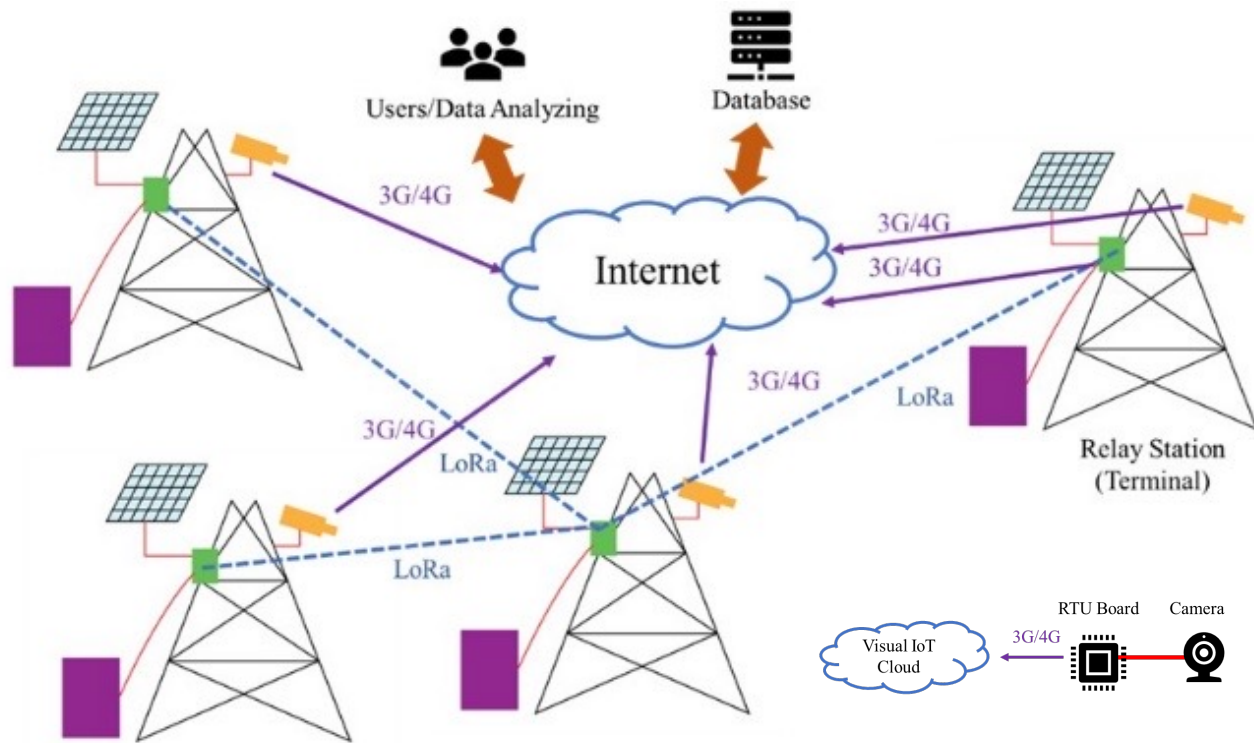
One of the leading causes of air pollution problems (e.g., PM2.5) is a forest fire. It is found that about 92% of burned area in Chiang Mai are in the conservation forest and national park. Furthermore, with the problem of high steep mountainous terrain in conservation and national parks and insufficient patrol staff, it is very difficult to do the effective monitoring and firefighting task with a quick response. Using Visual IoT in the forest fire monitoring system will increase the ability to accurately assess and provide information about the situation of the scene quickly. In this project, Visual IoT will be used in conjunction with other sensors such as satellite image in order to assess the situation of forest fire.

Targets:

- System of visual IoT cameras with transmission modules
- Algorithms for forest fire detection
- Data visualization



System Overview



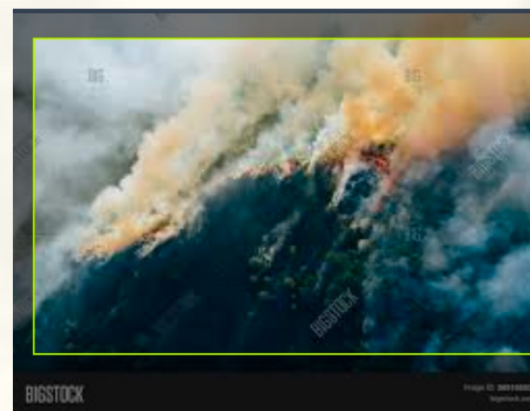
Example Of Available Datasets



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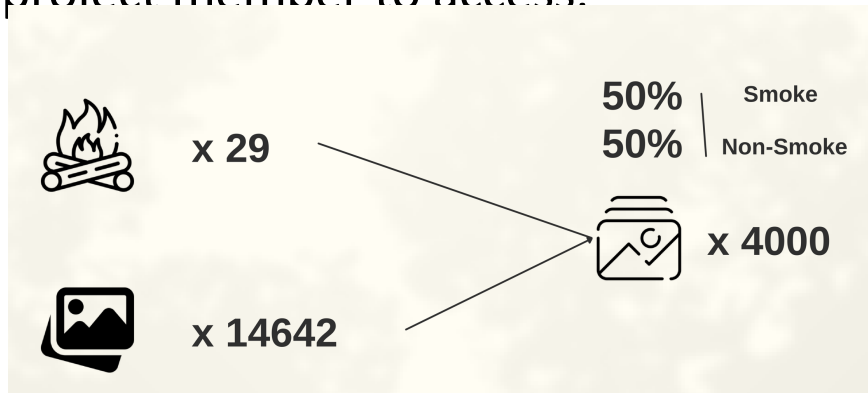
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Dataset construction

Field experiment for developing an image-based dataset have been conducted in all 3 targeted sub-districts.

The dataset is open for project member to access.

Area	Location	Total number of fire spots	#Photos taken
1. Huai Huk	lat 18.9245582, long 99.094015	8	4,355
2. Pa Maing	lat 18.9145094, long 99.2284893	7	3,977
3. Doi Koo 1	lat 18.8854613, long 99.1708773	5	2,580
4. Doi Koo 2	lat 18.885279, long 99.1706582	4	1,887
5. Pang Sak	lat 18.9026969, long 99.203065	5	1,843
Total number of photos taken in this field experiment			14,642



The procedural activities are summarized as follows.

- Local government officers responsible for setting fire were ready at a planned and designated position (fire spot)
- They made smoke for half an hour for one fire spot.
- Four cameramen, including one at the top of tower, were ready to take photos (snapshot and video) from before the appearance of smoke until it died out.
- Once the fire was set, the camerapersons took photos from different viewpoints simultaneously.
- Then, the local government staff moved to the following designated spot and repeated the procedure.



Meeting with local government officer



Local government staffs



Fire / smoke setting and extinguishment





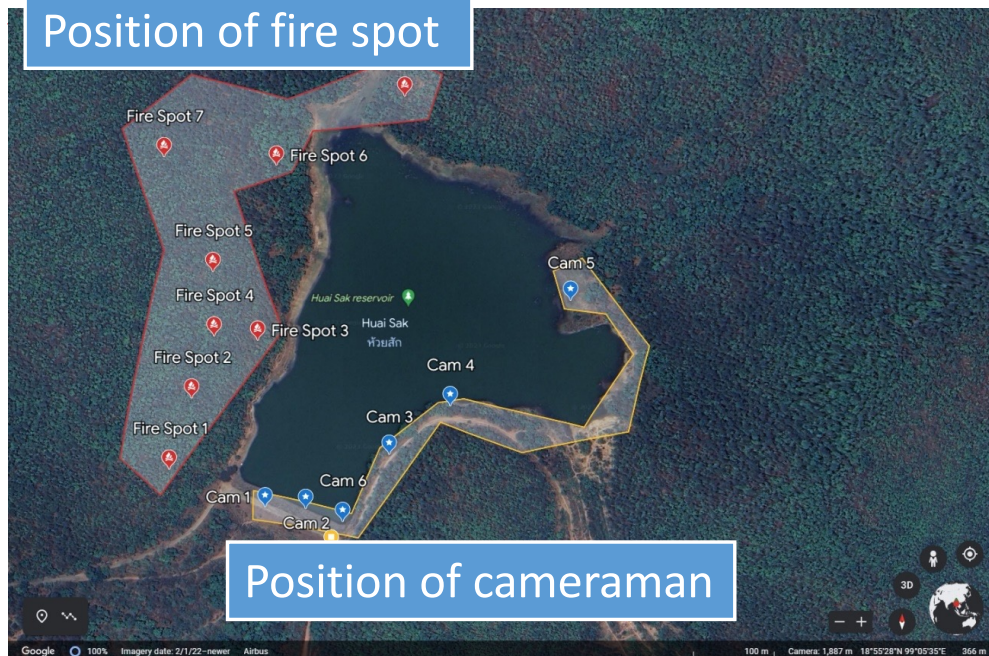
Cameraman at the top of tower



Example of taken image



Position of fire spot



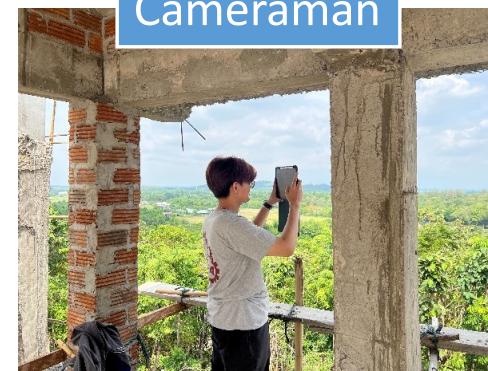
Position of cameraman

Experiment site at Hua Huk (Nong Yang sub-district)

Setting fire



Cameraman



Operational staffs



Hua Huk area

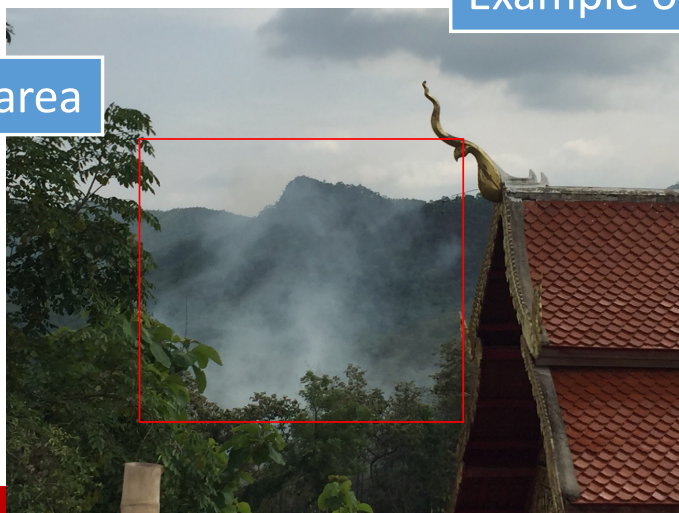


Pa Miang area

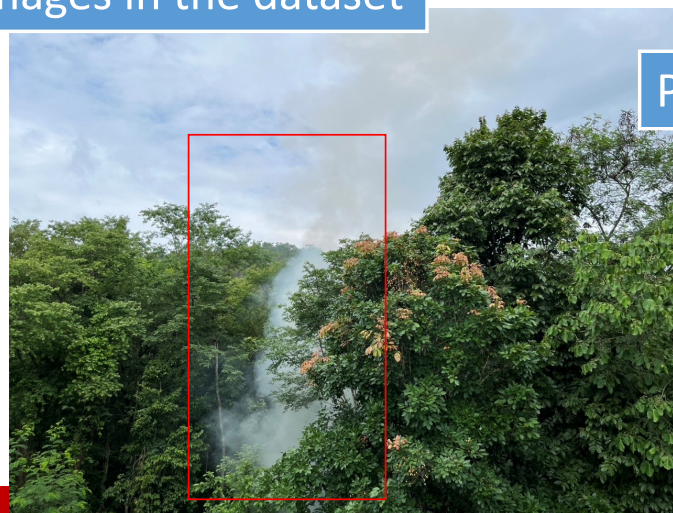


Example of images in the dataset

Doi Koo #1 area



Pang Sak area



Our dataset



YOLOv5

$$F_1 = 2 \cdot \frac{\text{precision} \cdot \text{recall}}{\text{precision} + \text{recall}} = \frac{TP}{TP + \frac{1}{2}(FP + FN)}$$

$$\text{Precision} = \frac{TP}{TP + FP}$$

$$\text{Recall} = \frac{TP}{TP + FN}$$

TP = number of true positives

FP = number of false positives

FN = number of false negatives

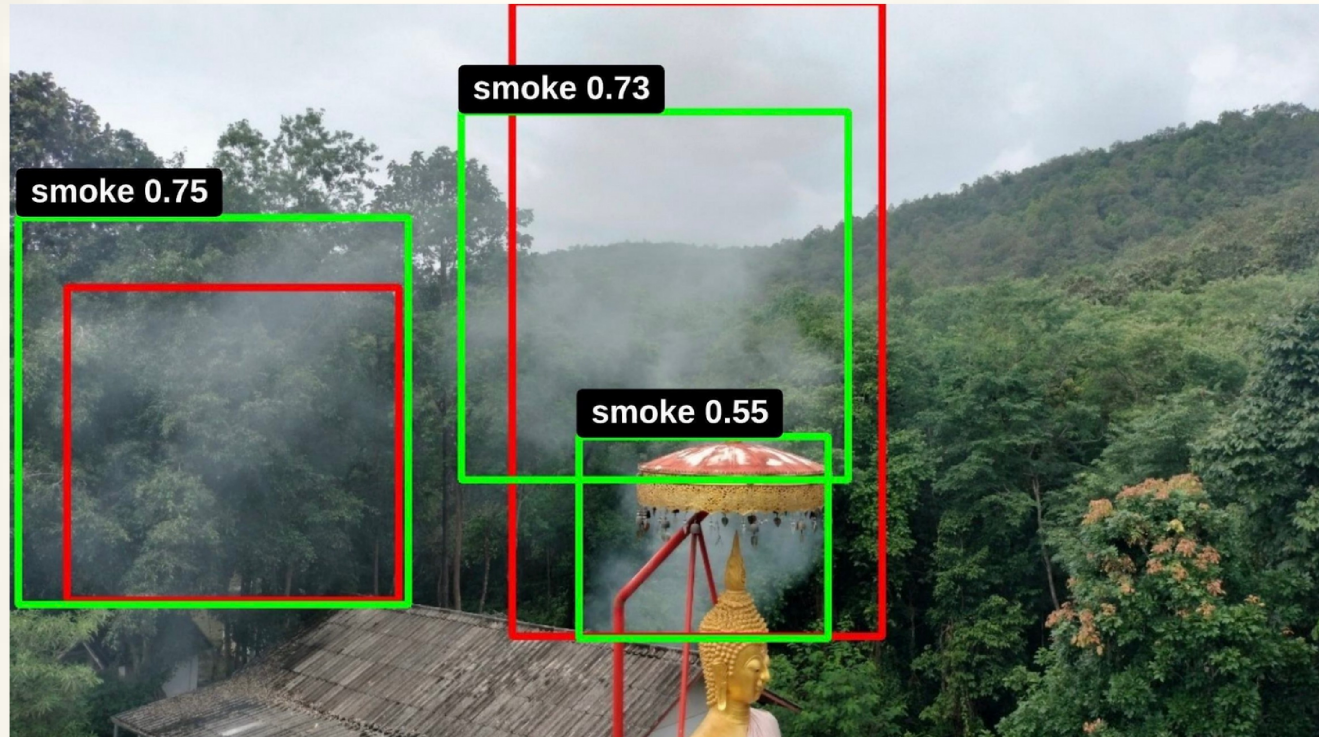
The evaluation metrics

Metrics of 4-fold cross validation

Round	Precision	Recall	mAP_0.5	mAP_0.5:0.95	F1-score
1	0.8171	0.7198	0.7809	0.3547	0.9688
2	0.7749	0.7228	0.7693	0.3435	0.9605
3	0.8055	0.7207	0.7772	0.3332	0.97
4	0.7631	0.6948	0.7364	0.3359	0.9616

Custom Evaluation

- image with smoke is counted as a TP if the model detects at least one smoke area with an IoU value larger than a predefined threshold; otherwise, it is considered a FN.
- image without smoke is counted as a TN if the model detects no smoke objects; otherwise, it is considered a FP.



Performance evaluation of our YOLOv5 – based smoke detection

IoU Threshold	Accuracy	Precision	Recall	F1-score	Balanced Accuracy
0.3	0.9388	0.974	0.9375	0.9554	0.9396
0.4	0.9375	0.974	0.9357	0.9545	0.9387
0.5	0.9375	0.974	0.9357	0.9545	0.9387
0.6	0.9363	0.9739	0.9339	0.9535	0.9378
0.7	0.9338	0.9738	0.9304	0.9516	0.936

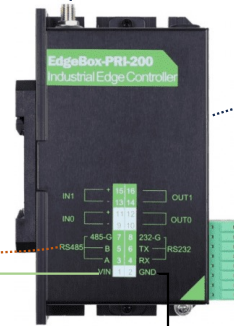
Solar cell

Hardware design & installation



IP camera

EdgeBox RPi 200 Controller



5G Antenna

5G (600~6000Mhz)
4G (698~2700Mhz)

LAN Cable

5G Antenna Cable

Main Controller

Encloser

Solar cell charge controller



RS485 Cable

DC Surge Protection

DC Circuit breaker

+12V to Load

Ground to Load

solar cell +V

solar cell -V

Earth ground

Battery

+V Battery

Temperature Sensor

Battery Encloser

RS485 Pinout on Charge Controller

Pinout on EdgeBox RPi 200 Controller

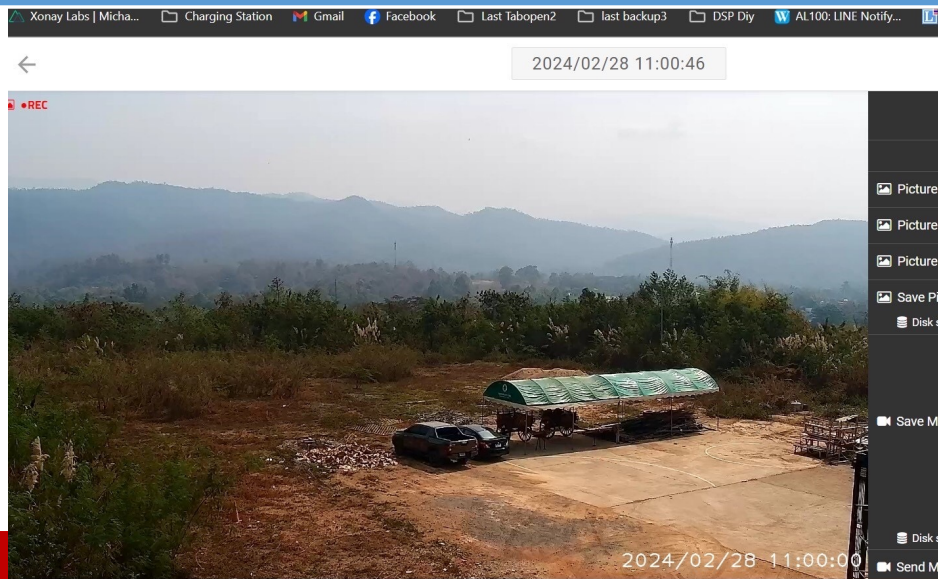
NECTEC
a member of NSTDA

Forest Fire Monitoring

System diagram



System installation and sample image at Pa Miang area





System installation and sample image at Huay Hug are



- Visual IoT system has been used for detecting smoke or early stage of forest fire in Chiang Mai (Thailand) and Myanmar
- 4,000 images of the dataset have been constructed
- Prediction of smoke/fire using YOLOv5 return accuracy of 93.88 %
- 5 sets of Visual IoT system have been installed in 3 targeted sub-district in Chiang Mai since Mar 1, 2024

Contact us



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